

What Is Claimed Is:

1. A method for a vehicle-related telematics service, having a central computer (server) and a data terminal, which is preferably arranged in the motor vehicle and between which a communication connection is established, wherein the telematics service is divided into partial functionalities, which in turn are subdivided between server and data terminal, functionalities that are not critical with respect to time running in the server, and functionalities that are critical with respect to time running in the data terminal.
2. The method for a vehicle-related telematics service, including a central computer (server), which establishes a communication connection with a data terminal, wherein the telematics service is subdivided into partial functionalities, and functionalities that are not critical with respect to time run in the server.
3. The method for a vehicle-related telematics service, including a data terminal, which is preferably arranged in the motor vehicle and establishes a communication connection with a central computer (server), wherein the telematics service is subdivided into partial functionalities, and functionalities that are critical with respect to time run in the data terminal.
4. The method as recited in one of the preceding claims, wherein the partial functionalities that are critical with respect to time run in the data terminal in an autonomous manner, and the partial functionalities that are not critical with respect to time are implemented by the server via communication with the data terminal.

5. The method as recited in one of the preceding claims, wherein the time-critical communication with a control unit to be diagnosed and/or a component to be diagnosed is implemented in the data terminal.

6. The method as recited in one of the preceding claims, wherein the telematics service is a remote diagnosis of a motor vehicle and the diagnosis protocol is implemented in the server.

7. The method as recited in one of the preceding claims, wherein commands of the vehicle-specific diagnosis protocol are transmitted via an air interface from the server to the data terminal.

8. The method as recited in one of the preceding claims, wherein the data terminal implements the transmitted diagnosis commands onto a vehicle network and transmits the generated response messages to the mobile radio interface.

9. The method as recited in one of the preceding claims, wherein KWP2000 or a variant thereof is used as diagnosis protocol.

10. A device for a vehicle-related telematics service, having
a central computer (server) and a data terminal, which is preferably arranged in the motor vehicle and between which a communication connection is established, wherein the telematics service is divided into partial functionalities, which in turn are subdivided between server and data terminal.

11. The device for a vehicle-related telematics service, having a central computer (server), which establishes a

communication connection with a data terminal, wherein the telematics service is subdivided into partial functionalities, and functionalities that are not critical with respect to time run in the server.

12. The device for a vehicle-related telematics service, having a data terminal, which is preferably arranged in the motor vehicle and establishes a communication connection with a central computer (server), wherein the telematics service is divided into partial functionalities, and functionalities that are critical with respect to time run in the data terminal.

13. The device as recited in Claim 10 or 11, the server communicating with the data terminal via an air interface, wherein the telematics service is a remote diagnosis of a motor vehicle, the diagnosis protocol being implemented in the server as partial functionality that is not critical with respect to time.

14. The device as recited in Claim 10 or 12, the data terminal communicating with the server via an air interface and including a further interface by which it is connected to a unit to be diagnosed, wherein the data terminal includes a sequence control as partial functionality that is critical with respect to time, the sequence control being autonomous with respect to the central computer unit and maintaining the diagnosis communication in the vehicle.

15. A computer program having program code means for carrying out all the steps of any of the Claims 1 through 9 when the program is executed on a computer.

16. A computer program product having program-code means, which are stored on a computer-readable data carrier in order to carry out the method according to any of Claims 1 through 9 when the program product is executed on a computer.